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Entropic Lattice Boltzmann Method: an implicit Large-Eddy Simulation?

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Motivations

Context

Implicit SGS arising when stabilizing for $\nu \to 0$ a Lattice Boltzmann Method by equipping it with a H-theorem

Aim

Study the physical properties of this implicit sub-grid scale (SGS) model

Tool

Development a tool based on balance equations to check hydrodynamic recovery of simulated flows accross scales

Introduction to Lattice Boltzmann Method (LBM)

LBM Equation with a relaxation time $\tau \equiv \tau_0$ fixed

$$f_i(ec{x}+ec{c}_i\Delta t,t+\Delta t)-f_i(ec{x},t)=-rac{1}{ au_0}\left[f_i(ec{x},t)-f_i^{eq}(ec{x},t)
ight]$$

Macroscopic quantities: Density: $\rho = \sum_{i} f_{i}$ Momentum: $\rho \vec{u} = \sum_{i} f_{i} \vec{c}_{i}$



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Chapman-Enskog expansion: $\mathcal{O}(K_n^2), \mathcal{O}(M_a^3)$ $u = c_s^2(\tau - 0.5)\Delta t$

Weakly compressible Navier-Stokes with viscosity $\nu \equiv \nu_0$ fixed

 $\rho \partial_t u_i + \rho u_j \partial_j u_i = -\partial_i p + \partial_j \rho \nu \left(\partial_j u_i + \partial_i u_j \right) + \mathcal{O}(M_a^3) + \mathcal{O}(K_n^2)$

with c_s^2 the speed of sound is the lattice

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Instabilities arising as $\tau_0 \rightarrow 0.5 \iff \nu_0 \rightarrow 0$ at a fixed resolution Can we get rid of those instabilities?

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Entropic LBM (ELBM) equips a H-theorem by locally adaptating

 $\tau = \tau^{\text{eff}}(\vec{x}, t) = \frac{2\tau_0}{\alpha(f_i(\vec{x}, t))}$ where α has a non-linear dependency on $f_i(\vec{x}, t)$

[Karlin et al., 1999]

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In practice unconditionnally stable

 $\nu_{eff}(\vec{x}, t) = c_s^2 (\tau_{eff}(\vec{x}, t) - 0.5) \Delta t$ expression in terms of macroscopic quantities?

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► A guess was derived using Chapman-Enskog expansion assuming $\alpha \approx 2 \iff \tau^{\text{eff}} \approx \tau_0$ [Malaspinas *et al.*, 2008]

$$u_{eff}(\vec{x}, t) = \nu_0 + \nu_t^{\mathcal{M}}(\vec{x}, t) \text{ with } \nu_t^{\mathcal{M}}(\vec{x}, t) \propto -\frac{S_{\theta\kappa}S_{\kappa\gamma}S_{\gamma\theta}}{S_{\lambda\mu}S_{\lambda\mu}}$$

where $S_{ij} = \frac{1}{2}(\partial_i u_j + \partial_j u_i)$

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$$u_{eff}(\vec{x}, t) = \nu_0 + \nu_t^M(\vec{x}, t) \text{ with } \nu_t^M(\vec{x}, t) \propto -\frac{S_{\theta\kappa}S_{\kappa\gamma}S_{\gamma\theta}}{S_{\lambda\mu}S_{\lambda\mu}}$$

where $S_{ij} = \frac{1}{2}(\partial_i u_j + \partial_j u_i)$

Similar to a Smagorinsty model: $\nu_t(\vec{x}, t) = C \sqrt{S_{\theta \kappa} S_{\theta \kappa}}$

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$$\nu_{eff}(\vec{x}, t) = \nu_0 + \nu_t^{\mathcal{M}}(\vec{x}, t) \text{ with } \nu_t^{\mathcal{M}}(\vec{x}, t) \propto -\frac{S_{\theta\kappa}S_{\kappa\gamma}S_{\gamma\theta}}{S_{\lambda\mu}S_{\lambda\mu}}$$

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Objective: Numerically check the existence of this implied SGS

Kinetic energy balancing averaged over a sub-volume V

Averaged kinetic energy balance equation for $\nu = \nu_0$ fixed

$$LHS_{V}^{E} = \partial_{t} \left\langle \frac{\rho u_{i} u_{i}}{2} \right\rangle_{V}$$

= $- \left\langle u_{i} \partial_{i} \rho \right\rangle_{V} - \nu_{0} \left\langle \rho \left(\partial_{j} u_{i} + \partial_{i} u_{j} \right) \partial_{j} u_{i} \right\rangle_{V} + \nu_{0} \left\langle \partial_{j} \rho u_{i} \left(\partial_{j} u_{i} + \partial_{i} u_{j} \right) \right\rangle_{V}$
 $- \left\langle \partial_{j} \frac{\rho u_{i} u_{i}}{2} u_{j} \right\rangle_{V} + \left\langle u_{i} F_{i} \right\rangle_{V}$
= $RHS_{V}^{E, 1} + RHS_{V}^{E, 2} + RHS_{V}^{E, 3} + RHS_{V}^{E, 4} + RHS_{V}^{E, 5} = RHS_{V}^{E}$

where $\langle \dots \rangle_{V}$ denotes the average over a sub-volume V

Kinetic energy balancing averaged over a sub-volume V

Averaged kinetic energy balance equation for $\nu = \nu_0$ fixed

$$\begin{split} LHS_{V}^{E} &= \partial_{t} \langle \frac{\rho u_{i} u_{i}}{2} \rangle_{V} \\ &= - \langle u_{i} \partial_{i} \rho \rangle_{V} - \nu_{0} \langle \rho \left(\partial_{j} u_{i} + \partial_{i} u_{j} \right) \partial_{j} u_{i} \rangle_{V} + \nu_{0} \langle \partial_{j} \rho u_{i} \left(\partial_{j} u_{i} + \partial_{i} u_{j} \right) \rangle_{V} \\ &- \langle \partial_{j} \frac{\rho u_{i} u_{i}}{2} u_{j} \rangle_{V} + \langle u_{i} F_{i} \rangle_{V} \\ &= RHS_{V}^{E, 1} + RHS_{V}^{E, 2} + RHS_{V}^{E, 3} + RHS_{V}^{E, 4} + RHS_{V}^{E, 5} = RHS_{V}^{E} \end{split}$$

Averaged kinetic energy balance equation for $\nu = \nu^{\text{eff}}(\vec{x}, t) = \nu_0 + \nu_t(\vec{x}, t)$

$$\begin{split} LHS_{V}^{E} &= \partial_{t} \langle \frac{\rho u_{i} u_{i}}{2} \rangle_{V} \\ &= - \langle u_{i} \partial_{i} p \rangle_{V} - \nu_{0} \langle \rho \left(\partial_{j} u_{i} + \partial_{i} u_{j} \right) \partial_{j} u_{i} \rangle_{V} + \nu_{0} \langle \partial_{j} \nu \rho u_{i} \left(\partial_{j} u_{i} + \partial_{i} u_{j} \right) \rangle_{V} \\ &- \langle \partial_{j} \frac{\rho u_{i} u_{i}}{2} u_{j} \rangle_{V} + \langle u_{i} F_{i} \rangle_{V} - \langle \nu_{t} \rho \left(\partial_{j} u_{i} + \partial_{i} u_{j} \right) \partial_{j} u_{i} \rangle_{V} + \langle \partial_{j} \nu_{t} \rho u_{i} \left(\partial_{j} u_{i} + \partial_{i} u_{j} \right) \rangle_{V} \\ &= RHS_{V}^{E, 1} + RHS_{V}^{E, 2} + RHS_{V}^{E, 3} + RHS_{V}^{E, 4} + RHS_{V}^{E, 5} + RHS_{V}^{E, 6} + RHS_{V}^{E, 7} \\ &= RHS_{V}^{E} \end{split}$$

where $\langle \ldots \rangle_{V}$ denotes the average over a sub-volume V

Periodic 256 \times 256 grid using a D2Q9 lattice

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Forcing on a shell of wavenumber

$$F_{\Psi}^{T} = F_{0}^{T} \sum_{\|\vec{k}\|=5}^{7} \cos\left(\frac{2\pi}{L}\vec{k}.\vec{x} + \phi\right)$$

where ϕ is an arbitrary constant

Periodic 256 \times 256 grid using a D2Q9 lattice



When forcing at k_f , we have:

- a backward energy cascade to large scales
- a forward enstrophy cascade to small scales

[Boffetta & Ecke, 2012]

Periodic 256 \times 256 grid using a D2Q9 lattice



- a backward energy cascade to large scales
- a forward enstrophy cascade to small scales

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 $E(k)/\varepsilon_{\alpha}^{2/3}$ 10^{-4}

10-6

10-8 10-10

Kinetic energy balancing error

$$\delta_{V}^{E}(t) = \frac{\left|RHS_{V}^{E}(t) - LHS_{V}^{E}(t)\right|}{\max_{i}\left|RHS_{V}^{E,i}(t)\right|}$$

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For a scale *L*, we gather statistics of δ_L^E : Balancing error over sub-volumes of shape $V = L \times L$ in space and time

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Example of sub-volumes shown on a vorticity field



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Kinetic energy balancing error $\delta_{V}^{E}(t) = \frac{|RHS_{V}^{E}(t) - LHS_{V}^{E}(t)|}{\max_{i} |RHS_{V}^{E,i}(t)|}$

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Kinetic energy balancing error

$$\delta_{V}^{E}(t) = \frac{|RHS_{V}^{E}(t) - LHS_{V}^{E}(t)|}{\max_{i} |RHS_{V}^{E,i}(t)|}$$

We process outputs from simulations that have reached statistical stationnarity

Example of sub-volumes shown on a vorticity field



For a scale *L*, we gather statistics of δ_L^E : Balancing error over sub-volumes of shape $V = L \times L$ in space and time

Evolution of the kinetic energy balancing on a single sub-volume $V = 181 \times 181$ for a LBM simulation with $\tau \equiv \tau_0 = 0.55$ fixed



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LBM for different fixed $\tau \equiv \tau_0 \rightarrow$ 0.5: Superposed spectrum



where $\tau_{last} = 0.515$ is the lowest τ ensuring a stable LBM simulation at this resolution and forcing amplitude

LBM for different fixed $\tau \equiv \tau_0 \rightarrow 0.5$: δ_L^E and $Ma_L = \frac{\langle u_{RMS} \rangle_L}{c_s}$



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LBM for different fixed $\tau \equiv \tau_0 \rightarrow 0.5$: δ_L^E and $Ma_L = \frac{\langle u_{RMS} \rangle_L}{C_e}$



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Entropic LBM for different $\tau_0 \rightarrow 0.5$: Superposed spectrum

 $\tau = \tau^{\text{eff}}(\vec{x}, t) = \frac{2\tau_0}{\alpha(\mathfrak{h}(\vec{x}, t))}$ & Constant forcing amplitudes



Entropic LBM for different $\tau_0 \rightarrow 0.5$: Superposed spectrum

 $\tau = \tau^{\text{eff}}(\vec{x}, t) = \frac{2\tau_0}{\alpha(f_i(\vec{x}, t))}$ & Constant forcing amplitudes



ELBM has the dissipative properties expected from a LES

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Entropic LBM for $\tau_0 = 0.515$: Correlation between ω and τ^{eff}

Snapshot of $\tau^{eff}(\vec{x}, t) = \frac{2 \tau_0}{\alpha(f_i(\vec{x}, t))}$



Effective relaxation time

0,51489 0,51493 0,51498 0,51503 0,51510

Snapshot of $\omega = \partial_x u_y - \partial_y u_x$



Vorticity

-2,143e-02 -0,0057 0,01 0,026 4,164e-02

Entropic LBM for $\tau_0 = 0.515$: Correlation between ω and τ^{eff}

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$au^{\it eff}$ adapts itself to vorticity peaks

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Entropic LBM: Validation of Malaspinas ν_t^M





Entropic LBM: Validation of Malaspinas ν_t^M





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Conclusions

- Developped a tool to check numerically the balance of kinetic energy and enstrophy accross scales
- Applied it to standard LBM:
 - Hydrodynamics is well recovered at large scales
 - Recovery at small-scales is less good
 - ► Enstrophy balance highlights higher order *M*_a terms
- Preliminary results on Entropic LBM:
 - Dissipative properties as $au_0
 ightarrow$ 0.5 are as expected for a LES
 - Malaspinas' ν^M_t(x, t) was numerically shown to be a 1st order expansion of ν_t(x, t) = ν^{eff}(x, t) − ν₀
 - As $\tau_0 \rightarrow 0.5$, τ^{eff} variance increase and ν^{eff} can become locally negative
- Systematic analysis of hydrodynamics recovery for Entropic LBM by adding Malaspinas SGS term to the balance equations is on-going





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Thank you for your attention!

Any questions?



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